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NO		

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H		√			
H		√	√		
H		√			
H		√			
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H		√	√		
H		√			
H		√			
H		√	√	√	√

1.5

OFF

- OFF

ON

- ON

			1	3	6	12
		√	√	√	√	√
					√	√
		√	√	√	√	√
		√	√	√	√	√
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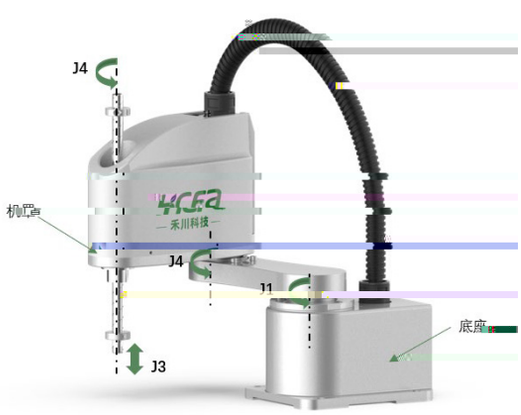

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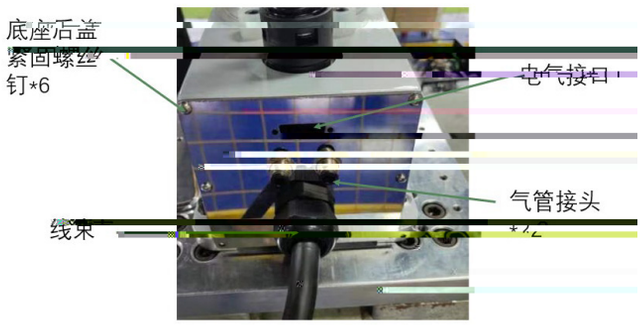
底座后盖
紧固螺丝
钉*6
电气接口
气管接头
*2
线束

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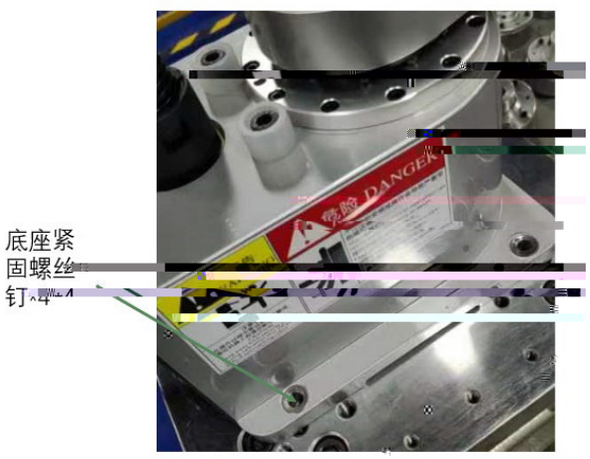
DANGER
底座紧
固螺丝
钉*4

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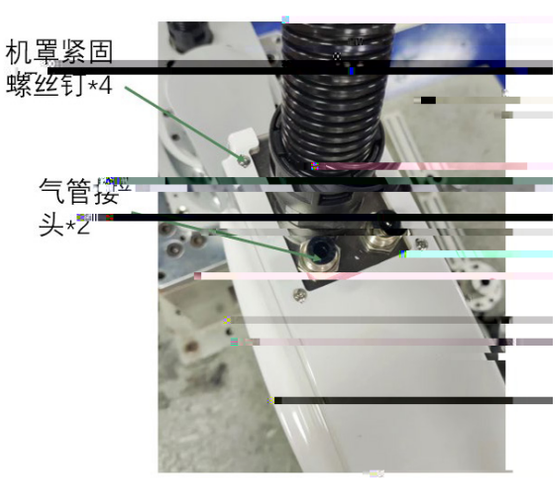
机罩紧固
螺丝钉*4
气管接
头*2

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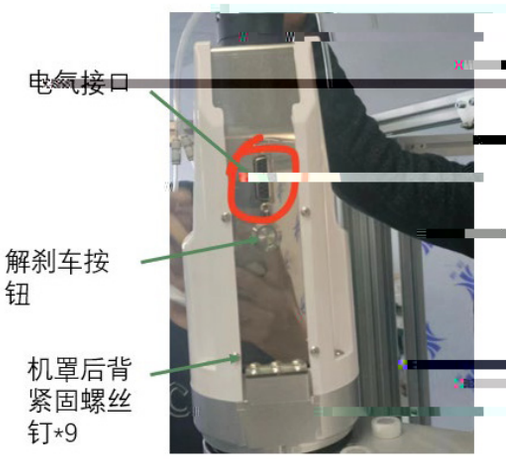
电气接口
解刹车按钮
机罩后背紧固螺丝钉*9

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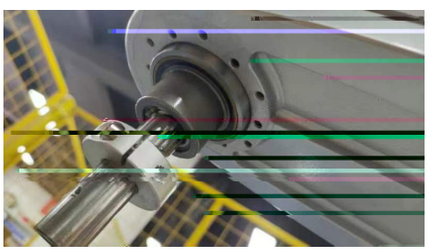

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手动、自动、远程模式拨钮
急停按键
显示屏

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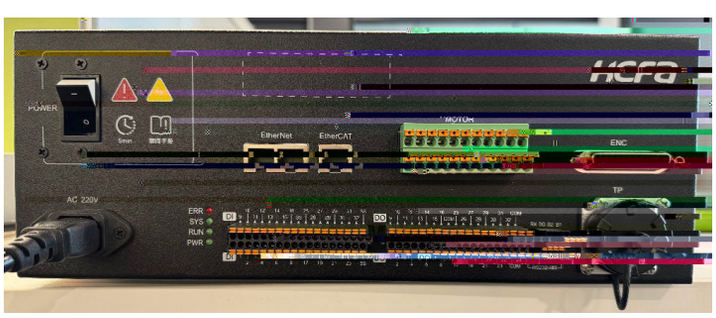
POWER
EtherNet
EtherCAT
MOTOR
ENC
TP
AC 220V
ERR
SYS
RUN
PWR

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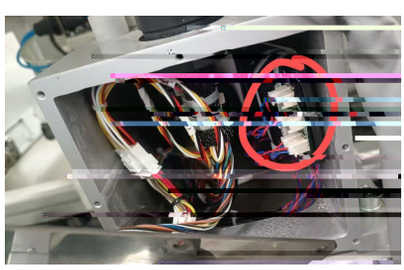

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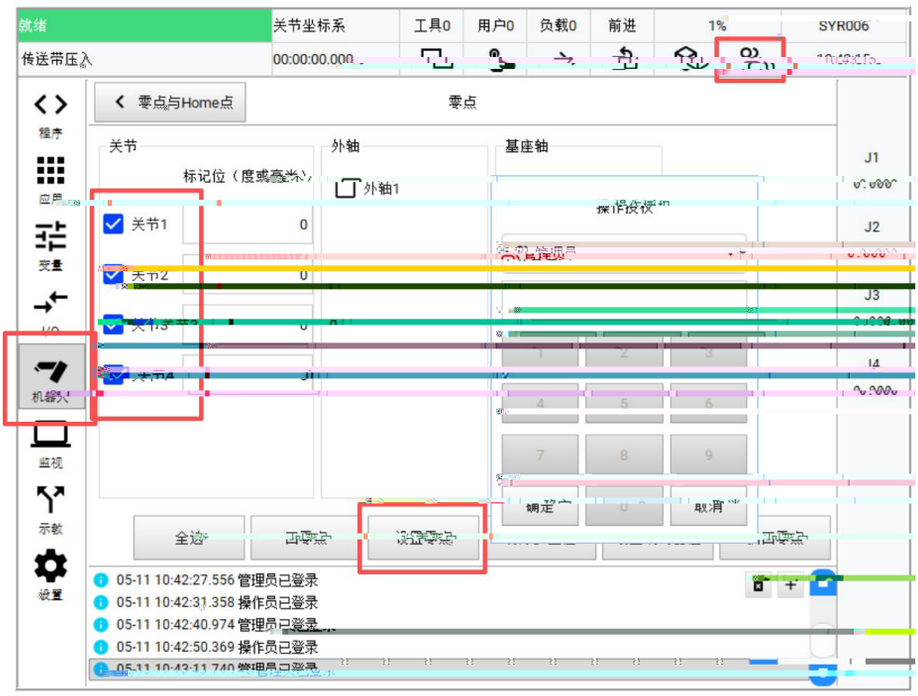
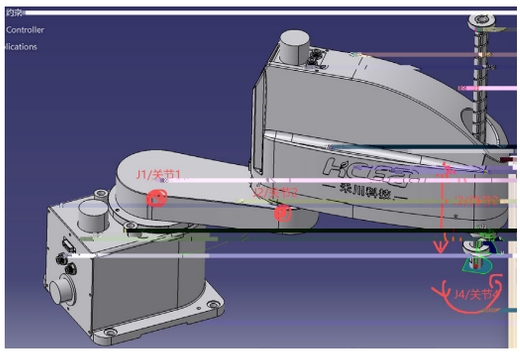
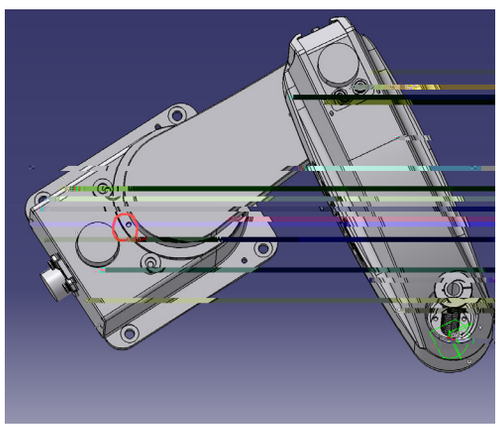
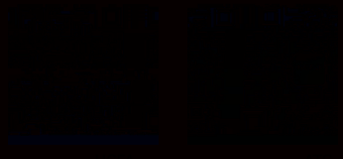

就绪
关节坐标系
工具0
用户0
负载0
前进
1%
SYR006
传送带压入
00:00:00.000
零点与Home点
零点
关节
外轴
基座轴
标记位（度或毫米）
外轴1
关节1
0
关节2
0
J1
J2
J3
J4
程序
应用
变量
I/O
机器人
监视
示教
设置
全选
05-11 10:42:27.556 管理员已登录
05-11 10:42:31.358 操作员已登录
05-11 10:42:40.974 管理员已登录
05-11 10:42:50.369 操作员已登录



D -

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